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is no force on the

xy-plane, the center of

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top has four degrees

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of freedom, namely the position of the center of mass and the three Euler angles. We choose the space fixed axes where the xy plane is the plane of the table and the the body fixed axes as one along the symmetry axis of the top, and the remaining two are arbitrary.

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take $z = 4cy^2$ we can

write the lagrangian

equations for this

motion $\frac{1}{2} m \dot{r}^2 - \frac{1}{2} m \dot{z}^2 -$

$\frac{1}{2} m \dot{\theta}^2 - m g z$ in our case

$r = y$ and $z = cy^2$ so we

can say that $\dot{z} = 2cy\dot{y}$

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